

EUROPEAN PATENT APPLICATION

Application number: 89830295.5

Int. Cl.⁵: **B 23 K 37/04**

Date of filing: 27.06.89

Priority: 13.07.88 IT 6766188

Date of publication of application:
17.01.90 Bulletin 90/03

Designated Contracting States:
AT BE CH DE ES FR GB GR LI LU NL SE

Applicant: **COMAU S.p.A.**
Via Rivalta 30
I-10095 Grugliasco (Torino) (IT)

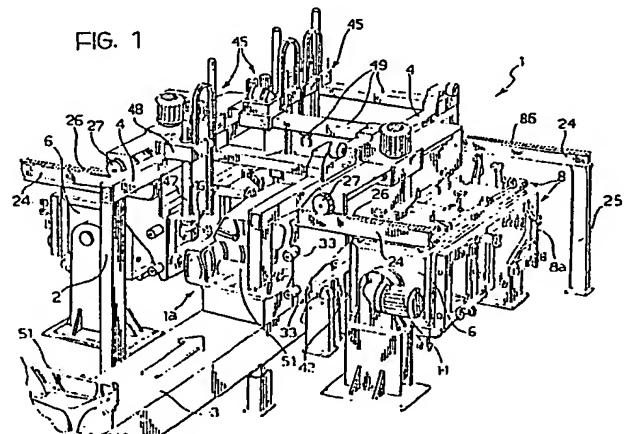
Inventor: **Alborante, Giancarlo**
Via Aldo Moro, 1
I-10028 Trofarello (Torino) (IT)

Graciotti, Rinaldo
Corso Laghi, 81/105
I-10090 Buttigliera Alta (Torino) (IT)

Representative: **Notaro, Giancarlo et al**
c/o Jacobacci-Casetta & Perani S.p.A. Via Alfieri, 17
I-10121 Torino (IT)

Apparatus for welding motor vehicle bodies.

Apparatus for welding loosely pre-assembled motor vehicle bodies (51) comprises a station (1) for locating and welding the body, a conveyor line (3) for transporting the loosely preassembled bodies (51) to the station (1), at least two pairs of locating gates (8) situated at the two sides of the station (1), each pair of locating side gates (8) being provided with locating devices (9) engageable with the body (51) and adapted to the specific geometric shape of a particular type of body, gate conveyor means for bringing a pair of side gates (8) corresponding to the type of body which is in the welding station (1) into correspondence with an operative position in the welding station (1), and at least one welding device (10) for welding the body. At least one drum (6) rotatable about an axis parallel to the longitudinal direction of the body in the welding station and carrying on its periphery a plurality of locating gates (8) suitable for various types of body is provided on each side of the conveyor line.



Descripti n

Apparatus for welding motor vehicle bodies

The present invention relates to apparatus for welding loosely pre-assembled motor vehicle bodies, of the type comprising:

- a framing station for locating and welding the body,
- a conveyor line for transporting the loosely preassembled bodies through the station,
- at least two pairs of locating gates situated at the two sides of the station, each pair of locating side gates being provided with locating devices engageable with the body and adapted to the specific geometric shape of a particular type of body,
- gate conveyor means for bringing a pair of locating gates corresponding to the type of body which is in the welding station into correspondence with a position in the welding station, and
- at least one welding device for welding the body in the welding station.

An apparatus of the type indicated above is described and illustrated in the same Applicant's German patent No. 2,810,822 and in the corresponding US patent No. 4,162,387.

The object of the present invention is to provide an apparatus of the type specified above, which is able to operate on a relatively large number of different body types and which at the same time occupies a reduced space longitudinally of the welding station.

In order to achieve this object, the subject of the invention is an apparatus of the type indicated at the beginning of the present description, characterised in that at least one drum member rotatable about an axis parallel to the longitudinal direction of the body in the welding station and carrying on its periphery a plurality of locating gates suitable for different types of body is provided on each side of the conveyor line.

In a preferred embodiment, the two drum members are arranged at the two sides of the working position in the welding station and means are provided for taking the locating gate which faces the working position from each drum member and moving it transverse the longitudinal direction of the welding station to an operative position in which the locating devices of the gate engage the body which is in the working position, and, conversely, for returning the locating gate from the operative position to its coupled position on the rotary drum.

When a body arrives at the welding station, a corresponding pair of locating gates is brought into the operative position in which the respective locating devices engage the various parts of the body to clamp them in their correct positions of assembly, whilst the welding devices effect a sufficient number of electrical spot welds to provide the structure with a relatively stable configuration. Upon the completion of such so-called "framing" operation, the body is discharged from the welding station and replaced by a new body to be welded. If the body entering the welding station is of a different type from that welded before, the locating gates previously used in the working position are returned

to the respective rotary drums and the latter are rotated so as to bring the two locating gates which correspond to the new type of body to be welded into positions facing the working position. When the rotation has been carried out, the two locating gates to be used are moved transversely away from their positions on the rotary drums, until they are brought into engagement with the body to be welded.

Moreover, in the preferred embodiment, each locating gate also carries a plurality of welding guns whose electrodes are connected to terminal contacts provided on the locating gate. Fixed electrical supply means for the welding guns are provided in correspondence with the working position in the welding station, and include a pair of contacts which can engage the terminal contacts carried by the locating gate when the latter is in its operative position. Preferably, the welding station is also provided with welding robots suspended in raised positions above the working position of the welding station.

Further characteristics and advantages of the invention will become clear from the description which follows with reference to the appended drawings, in which:

Figure 1 is a schematic perspective view of welding apparatus according to the invention,

Figure 2 is a schematic plan view of the apparatus of Figure 1,

Figure 3 is a section taken on the line III-III of Figure 2,

Figure 4 is a section taken on the line IV-IV of Figure 2,

Figure 5 is a section taken on the line V-V of Figure 4,

Figure 6 is a section of the detail indicated by the arrow VI in Figure 5, on an enlarged scale,

Figure 7 is a section of the detail indicated by the arrow VII of Figure 4, on an enlarged scale,

Figure 8 is a section of the detail indicated by the arrow VIII of Figure 4, on an enlarged scale,

Figure 9 is a view of the detail indicated by the arrow IX of Figure 3, on an enlarged scale,

Figure 10 is a schematic view of the electrical supply system of the welding guns situated on a forming frame, and

Figures 11, 12 and 13 are a schematic side view, a schematic plan view and a schematic front view of a forming frame engaged with a motor vehicle body.

In Figures 1 to 4, a welding station according to the present invention is generally indicated 1. The station 1 comprises a fixed structure which, in the embodiment illustrated, includes two pairs of columns 2 situated at the two sides of a conveyor line 3 for transporting the bodies. Each pair of columns 2 arranged on one side of the conveyor line 3 is connected at the top by a longitudinal beam 4. The fixed structure is completed by two cross members 5 situated in correspondence with the ends of the longitudinal beams 4 and connecting the upper

ends of the columns 2 which are situated on these two sides of the conveyor line 3.

The central region within the fixed structure described constitutes the working position of the station, in correspondence with which the bodies to be welded are stopped in order to undergo the necessary welding operations.

According to the prior art of the same Applicant's German patent No. 2,810,822, the bodies are first loosely assembled and then brought to the welding station 1. The loose preassembly can be carried out, for example, by coupling the various sub-units of the body by means of the bending of tongue-like appendages ("toy tabs" in English terminology) on to adjacent parts of the body. Still according to the prior art described above, the station 1 provides for the positioning of the various parts of the body in the correct assembly position and the effecting of a sufficient number of spot welds to provide the structure with relative stability. The conveyor line 3 used for bringing the loosely preassembled bodies into the welding station and for carrying the welded bodies away from the welding station and to the subsequent stations (not illustrated) which complete the welding of the body is shown only schematically in the appended drawings. The details of the structure of the line 3 are not illustrated since this structure is of known type and does not fall within the scope of the present invention. Moreover, it is clear that, whilst the appended drawings illustrate schematically a transfer line which passes through the welding station, any alternative solution may be used for transporting the preassembled bodies into the welding station and for transporting the welded bodies away from the welding station. Various possible solutions in this connection are described, for example, in the cited German patent No. 2,810,822.

Again according to the prior art of the above patent, the welding station is provided with a plurality of pairs of locating frames or "gates" which are rapidly interchangeable in the operative position and each of which carries a series of locating devices intended to position the body correctly for the execution of the welding operations. The positioning devices of each pair of locating side gates are adapted to a specific type of body. The present invention particularly concerns a specific technique which can be used to achieve the rapid replacement of the pair of side gates situated in the operative position in order to enable the welding of a different body type.

In the device according to the invention, the different types of locating gates are arranged on each side of the line 3 on the periphery of a drum 6 which is mounted for rotation about an axis 7 parallel to the length of the body situated in the welding station.

In the preferred embodiment illustrated in the drawings, the two rotary drums 6 face the working position 1a in the welding station.

In the embodiment illustrated, each rotary drum 6 has four faces each carrying a locating gate 8 of a respective type. Each locating gate 8 comprises, in known manner, a substantially frame-like support

structure 8a (Figures 11, 12, 13) having its longer sides 8b directed longitudinally and two intermediate cross members 8d parallel to the shorter sides 8c. Naturally, the particular structure of the frame 8 which is illustrated in the appended drawings is given only by way of example. Locating and clamping devices 9 are fixed to the support structure 8a. The structure of the devices 9 is not shown in detail since it is of known type and does not fall within the scope of the present invention. The purpose of the clamping devices 9 is to position the various parts of the loosely preassembled body correctly and to clamp them in that position during the welding. The arrangement and shape of the devices 9 depend on the geometric shape of the body to be welded. In the preferred embodiment illustrated, each locating gate 8 is also provided with a series of welding guns 10 for the electrical spot welding of the body (Figures 11, 12, 13), each welding gun 10 comprising two electrodes 10a (Figure 13) carried by the jaws of the gun and being provided with an actuator cylinder 12 for operating its jaws. The means for the electrical supply of the electrodes of the welding guns and for the supply of fluid to the actuator cylinders of the guns will be described in detail below.

Each drum 6 is supported for rotation about the axis 7 by two columns 13, one of which has an associated electric operating motor 14 with a reduction device. The electric motor 14 is operated to rotate the rotary drum 6 and position the locating gate 8 corresponding to the type of body to be welded so that it faces the working position. Once this positioning has been effected, the locating gate to be used is removed (in the manner which will be described in detail below) from the rotary drum and brought adjacent the body to be welded so as to enable the clamping devices 9 and the welding devices 10 to engage the body.

Figure 4 shows the welding station in the condition in which two locating gates have been removed from the rotary drums 6 and brought into engagement with a body to be welded. Each locating gate is provided, on its face which faces the rotary drum, with a plurality of coupling pins 15 which enable the gate 8 to be coupled to the rotary drum 6. As shown in detail in Figure 7, when a locating gate 8 is situated in contact with the respective face of the rotary drum 6, each of the pins 15 is housed in a bush 16 mounted in a through-hole 17 formed in the wall 6a of the rotary drum. The clamping of the locating gate 8 to the rotary drum 6 is achieved by the engagement of a wedge 18, driven by an actuator cylinder (not visible in the drawings) mounted within the rotary drum 6, in a transverse hole 19 in each coupling pin 15 (see Figure 7).

In the appended drawings, only the locating gates 8 which are situated in the operative position in correspondence with the working position of the welding station are shown in detail, whilst the rest of the locating gates situated on the rotary drum are shown schematically in broken outline.

A slide device 20 is provided on each side of the welding station for moving the locating gate 8 which faces the working position between the position in which it is coupled to the rotary drum 6 and its

operative position adjacent the body to be welded. Each device 20 has a portal structure with an upper cross member 21 and two lateral legs 22 (Figure 5). The legs 22 are provided with wheels 23 (Figures 4, 5) which engage two lateral tracks defined by two I-sections 24 supported at their ends by the side members 4 and by columns 25 (Figures 1, 4).

The upper faces of the two sections 24 carry two racks 26 on which roll two ring gears 27 supported for rotation by the structure 20 and rotated, through shafts 28 arranged on a common axis along the cross member 21, by a central electric motor 29 and a reduction device 30 with two outputs (Figure 5). The operation of the motor 29 causes the rotation of the toothed columns 27 and the consequent movement of the structure 20 with the motor 29 and its transmission in a direction transverse the longitudinal direction of the welding station. In order to enable the coupling of a locating gate 8 to the device 20, the two vertical sides of each gate 8 have a pair of vertically spaced holes 31 (Figure 6), each of which has a bush 32 associated therewith. Each of the two legs 22 of the structure 20 has a pair of actuator cylinders 33 which cause the insertion of coupling pins 34 (Figure 6) into the bushes 32 and the consequent coupling of the gate 8 to the device 20. On the assumption that the locating gate 8 which faces the working position of the welding station is situated in the position in which it is coupled to the respective rotary frame 6, it is picked up by the device 20 firstly by the positioning of the device 20 in correspondence with the gate 8 to cause the engagement of the pins 34 in the bushes 32 of the gate 8 by the operation of the actuator cylinders 33, and then by the disengagement of the wedges 18 from the coupling pins 15 which lock the gate 8 to the rotary drum. Once the gate 8 has been loaded onto the device 20, the latter can be moved transversely by the operation of the motor 29 until the gate 8 is brought to the operative position (Figure 4) in which the clamping tools 9 and the welding guns 10 can engage the body to be welded. When the gate 8 reaches its operative position, its lower edge rises on rollers 34 with horizontal axes (Figure 3, Figure 8) which ensure the accuracy of the vertical positioning of the gate. At the same time, the accuracy of the horizontal positioning of the gate 8 is ensured by the engagement of the lower arm of the gate against a support wall 35 and by its clamping against this wall by means of a lever 36 (Figure 8) which is operated by an actuator cylinder 37 and is pivotable about an axis 38. When the lever 36 is in the operative position illustrated in Figure 8, it comes into engagement with the gate 8 on the side opposite that which is in contact with the support wall 35 so as to clamp the gate against the latter.

When the gate 8 is in its operative position, the pipes for the supply of fluid to the actuator cylinders of the welding guns, which are situated in the hollow structure of the gate 8, are put into communication with a fluid-supply source by means of a quick-coupling connector 39 which is raised automatically until it mates with a corresponding part provided in the locating gate 8. The details of this connector are not illustrated since they are of known type. In the

embodiment illustrated, the electrical supply of the welding guns 10 is achieved (Figure 10) by means of two separate electrical circuits which are connected to two pairs of terminals 40, 41 (Figure 10, Figure 3) provided in the lower part of the gate 8. Each of the terminals 40, 41 is engaged - when the gate 8 is in its operative position - by a clamp 42 operated by an actuator cylinder 43 (Figure 9), the two clamps 42 associated with each pair of terminals 40, 41 being connected in turn to the two terminals of an electrical supply transformer 44 (Figure 9). All the welding guns of each electrical circuit are therefore supplied by the same fixed electrical transformer.

Finally, three cartesian robots are provided in the upper part of the welding station and carry the same number of welding guns which cooperate with the welding guns carried by the forming gates 8 in the operative position so as to carry out the welding of the body which is in the station. Each of the robots - generally indicated 45 - has a head 46 carried by a slide 47 which can slide vertically relative to a further slide 48 which slides horizontally on a bridge 49 whose ends are mounted for sliding on two tracks 50 provided on the side members 4 of the welding station (Figures 1, 4). Each of the three axes of the robot is controlled by a respective electric operating motor. The structure of the robots is not described in detail, however, since it is of known type.

The operation of the system described above is as follows:

the conveyor line 3 brings successive bodies 51 to be welded to the working position in the welding station 1 with a stepwise movement. As already indicated, the bodies arrive at the welding station in a loosely preassembled condition. When a new body 51 arrives and stops in the welding station, the rotary drums 6 are already arranged with the locating gates of the type corresponding to the type of body to be welded in position facing the working position 1a. If the gate 8 is still attached to the rotary drum 6, the device 20 provided on each side of the station picks up the gate in the manner described above and places it in the operative position. In this position, the various clamping devices engage the body to position its various elements accurately after which the welding guns 10 carried by the locating gates 8 and the welding guns 46 carried by the robots 45 come into operation to effect the welding of the body. When the welding is completed, the clamping devices 9 open (as do the clamping levers 36) and the devices 20 retract the gates to enable the discharge of the welded body from the welding station and the entry of a new body to be welded. If the body arriving at the station is of the same type as that welded previously, the structures 20 do not return the gates 8 to the rotary drums but leave them in an intermediate waiting position and then, once the new body to be welded has reached the station, return them to the operative position. If the new body to be welded is of a different type from that welded previously, the locating gates 8 used previously are placed on the respective rotary drums and the latter are rotated until two location gates which correspond to the new type of body to be

welded are brought into position facing the working position. The devices 20 take the two frames 8 from the rotary drums and place them in the operative position as soon as the new body to be welded has reached the new working position.

As can be seen from the above description, the welding station according to the invention enables four different types of body to be operated on and at the same time occupies a very limited space longitudinally of the installation. Obviously, when the number of models to be operated on is other than four, rotary drums 6 with a corresponding number of faces are provided.

Naturally, the principle of the invention remaining the same, the forms of embodiment and details of construction may be varied widely with respect to those described and illustrated purely by way of non-limiting example.

Claims

1. Apparatus for welding loosely preassembled motor vehicle bodies, comprising:
a station for forming and welding the body (1),
a conveyor line (3) for transporting the loosely preassembled bodies through the station (1),
at least two pairs of locating gates (8) situated at the two sides of the station (1), each pair of locating gates (8) being provided with locating devices (9) engageable with the body (51) and adapted to the specific geometric shape of a particular type of body,
gate conveyor means for bringing a pair of locating gates (8) corresponding to the type of body to be welded into correspondence with a working position (1a) in the welding station, and
at least one welding device (10) for welding the body in the welding station,
characterised in that at least one drum member (6) rotatable about an axis (7) parallel to the length of the body in the welding station and carrying on its periphery a plurality of locating gates (8) suitable for different types of body is provided on each side of the conveyor line (3).

2. Apparatus according to Claim 1, characterised in that the two drum members (6) are situated at the two sides of the working position (1a), and in that means (20) are provided for taking a locating gate from each drum member (6) and moving it transversely to an operative position adjacent the body to be welded and vice versa to return the locating gate (8) from the operative position to the drum member (6).

3. Apparatus according to Claim 1, characterised in that each locating gate carries a plurality of welding guns (10) whose electrodes (10a) are connected to terminal contacts (40, 41) provided on the gate (8), and in that fixed electrical supply means (44) for the welding guns (10) are provided in correspondence with the working position (1a) of the welding station (1) and include a pair of clamp contacts (42) which can engage the terminal contacts (40, 41) carried by the forming frame (8).

4. Apparatus according to Claim 1, characterised in that each rotary frame has a polygonal cross-section and carries a locating gate (8) on each of its faces.

5. Apparatus according to Claim 2, characterised in that the means for moving the locating gate (8) transversely between the rotary drum (6) and the operative position comprise a portal structure (20) which is guided transversely on the fixed structure of the welding station and has lateral legs (22) provided with coupling pins (34) which are adapted to engage lateral holes (31) provided in the ends of each locating gate (8).

6. Apparatus according to Claim 1, characterised in that each locating gate has, on its face which faces the respective rotary drum (6), a plurality of coupling pins (15) which are intended to be housed in corresponding holes (17) in the rotary drum (6) and locked in the holes by means of transverse wedges (18) adapted to engage through-holes (19) formed in the coupling pins (15).

7. Apparatus according to Claim 1, characterised in that the top of the fixed structure of the welding station supports a plurality of cartesian robots (45) carrying welding guns.

8. Apparatus according to Claim 5, characterised in that means are provided for clamping each locating gate (8) in the operative position in order to ensure the correct positioning of the frame.

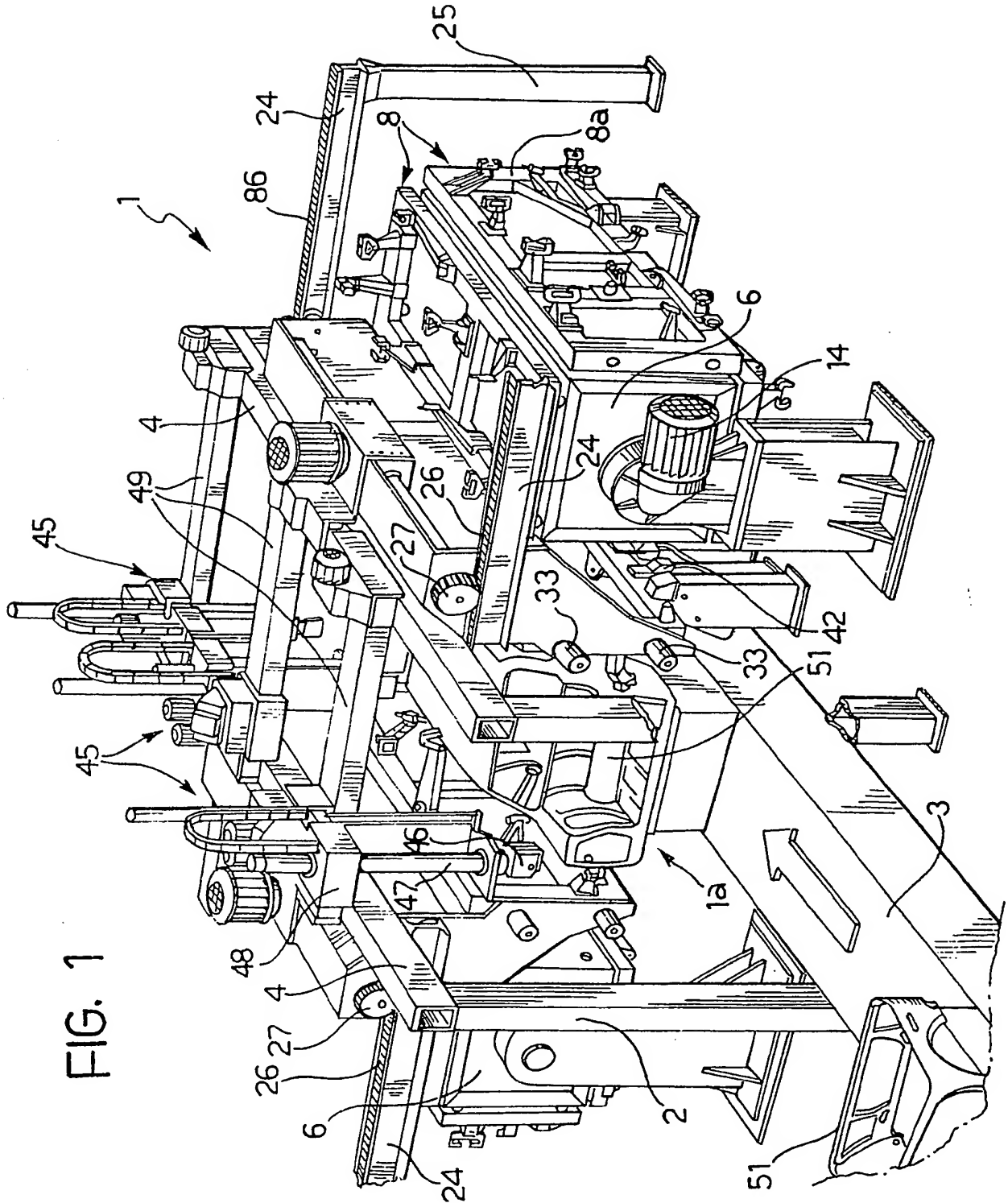


FIG. 2

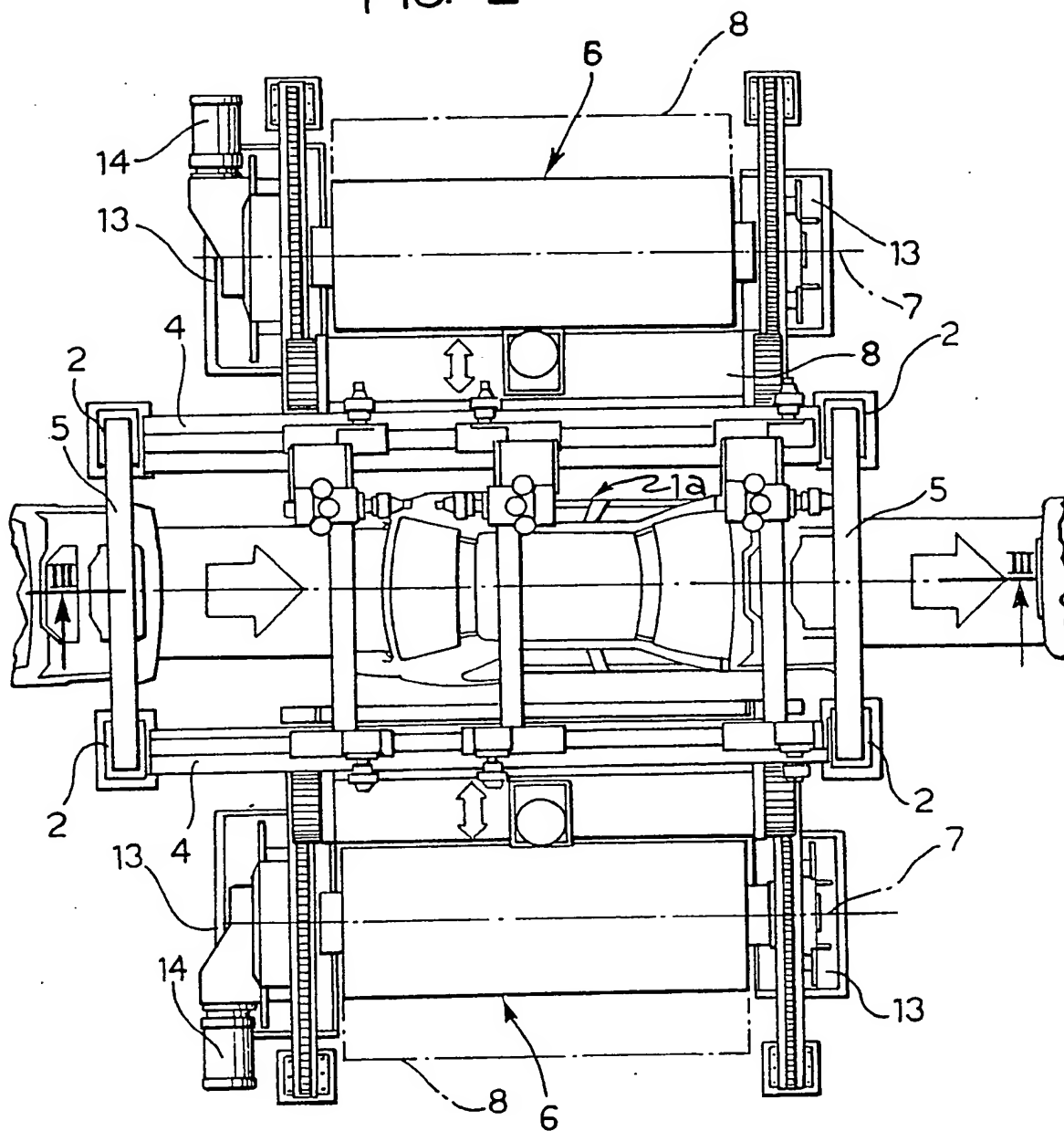
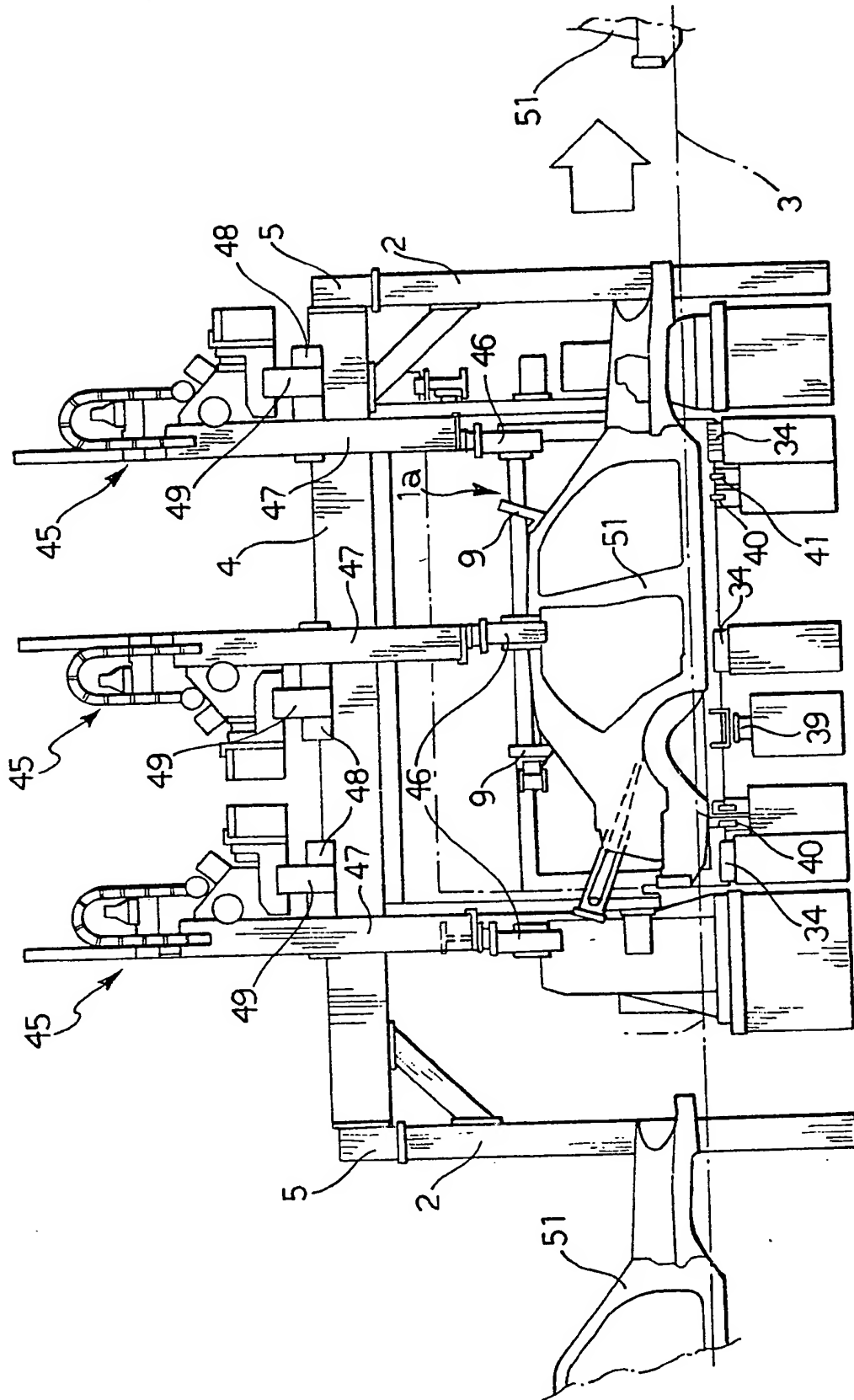


FIG. 3



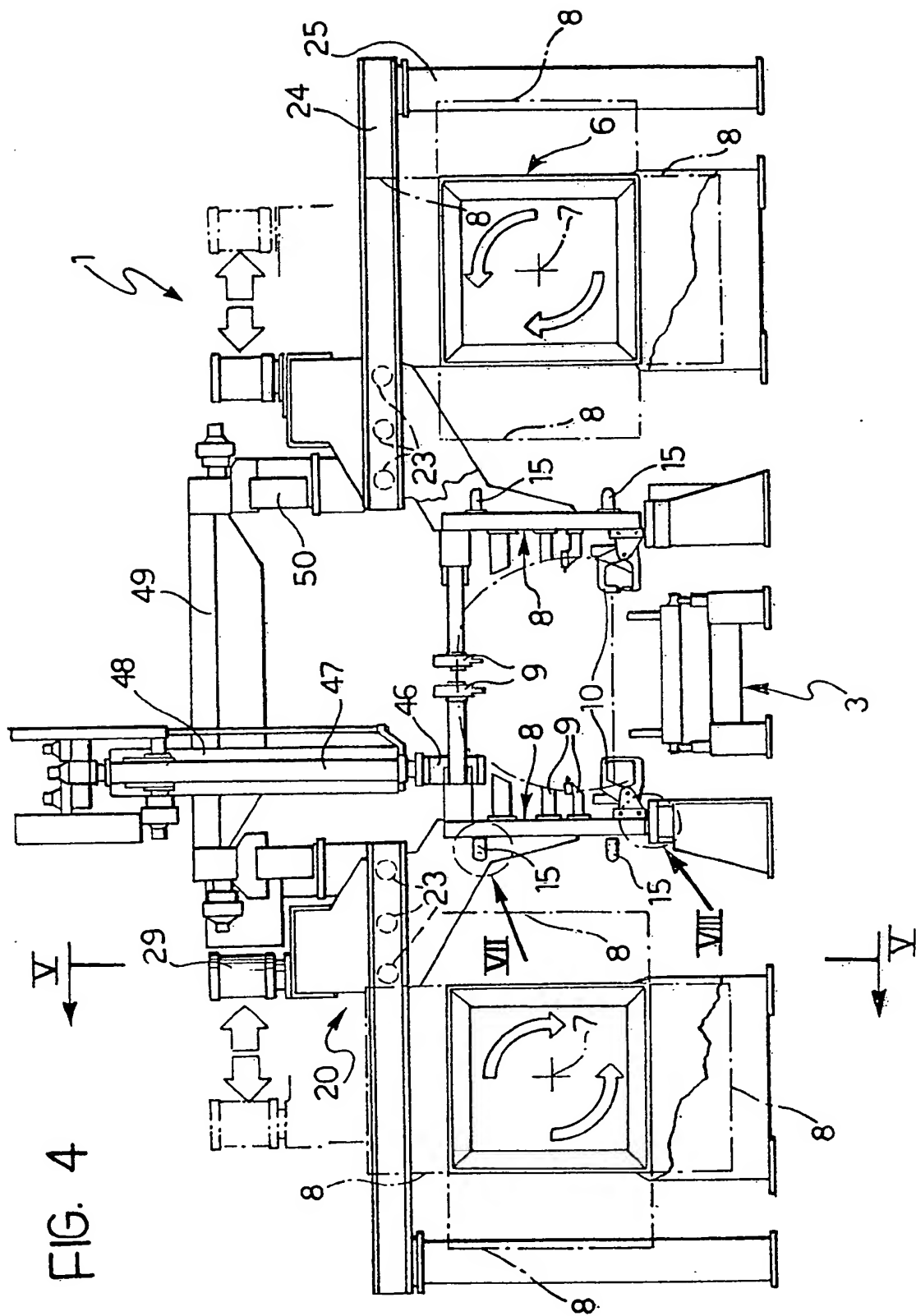


FIG. 5

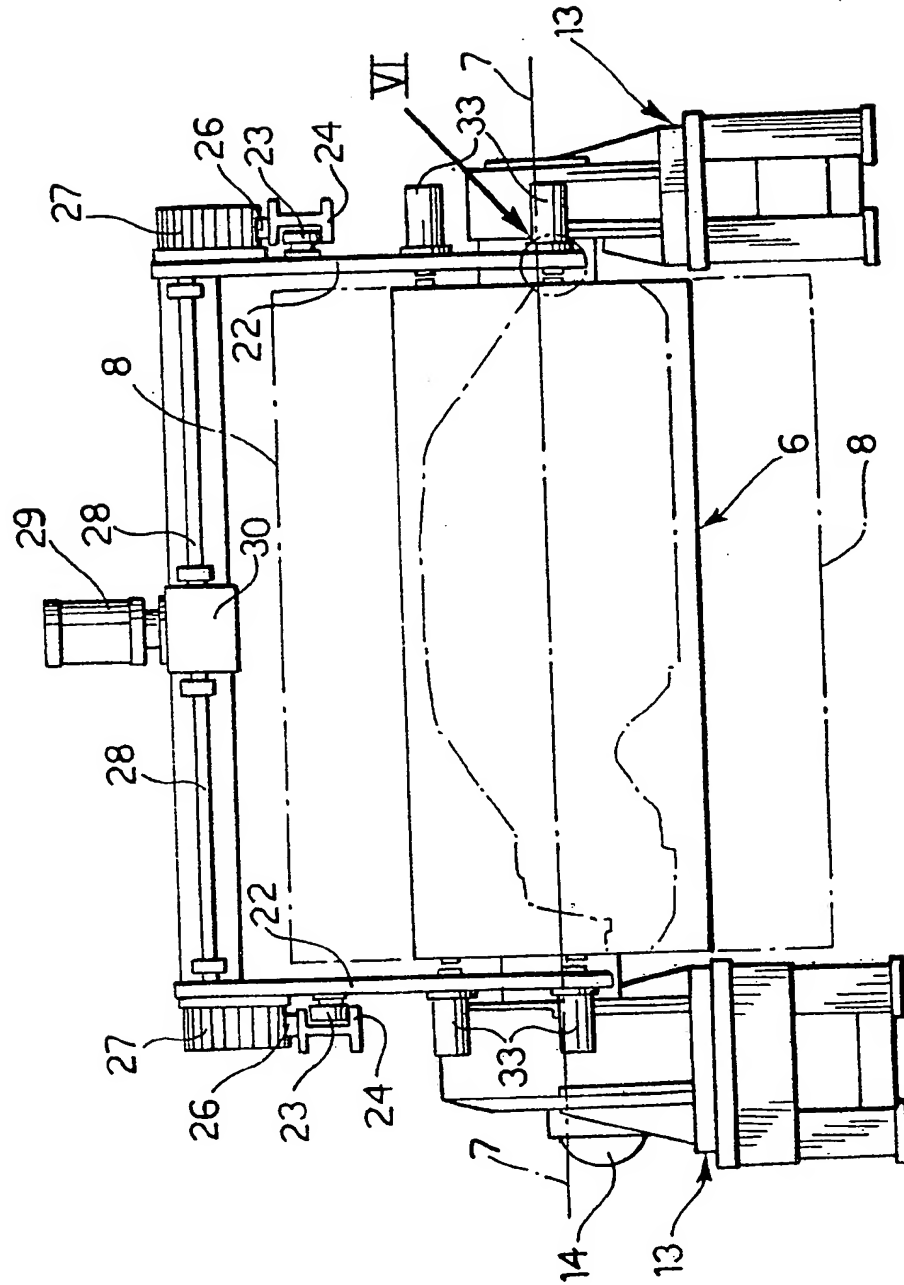


FIG. 7

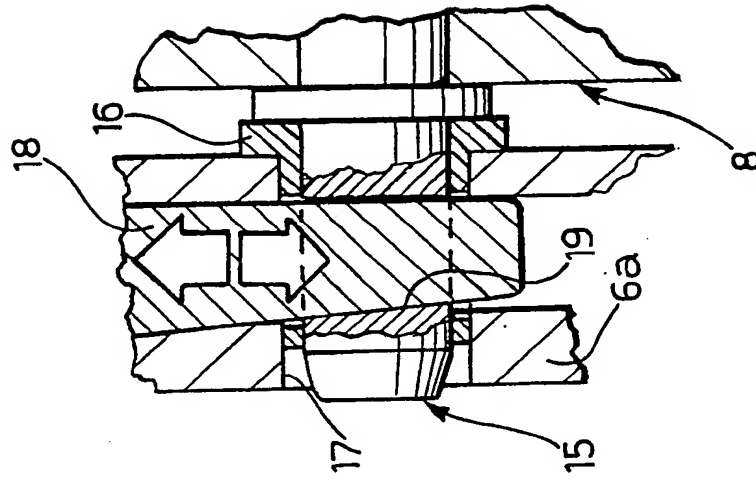


FIG. 6

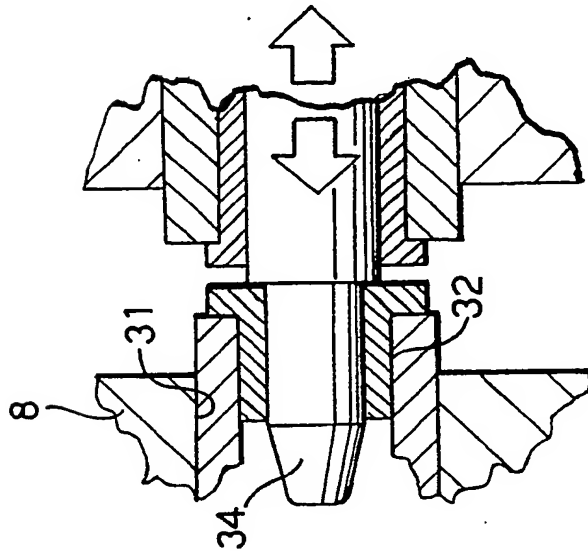


FIG. 8

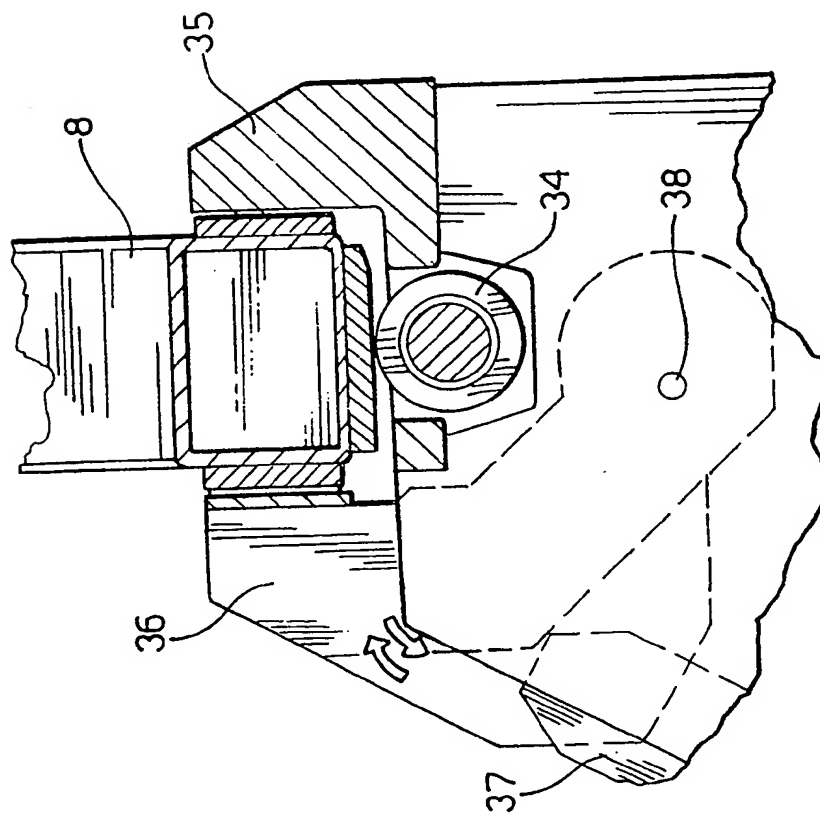


FIG. 9

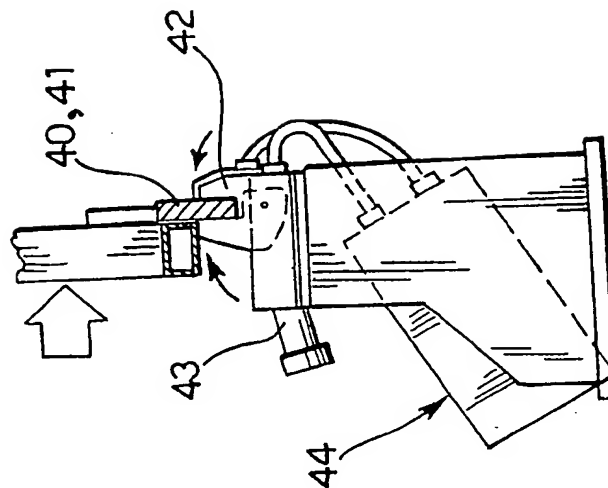


FIG. 13

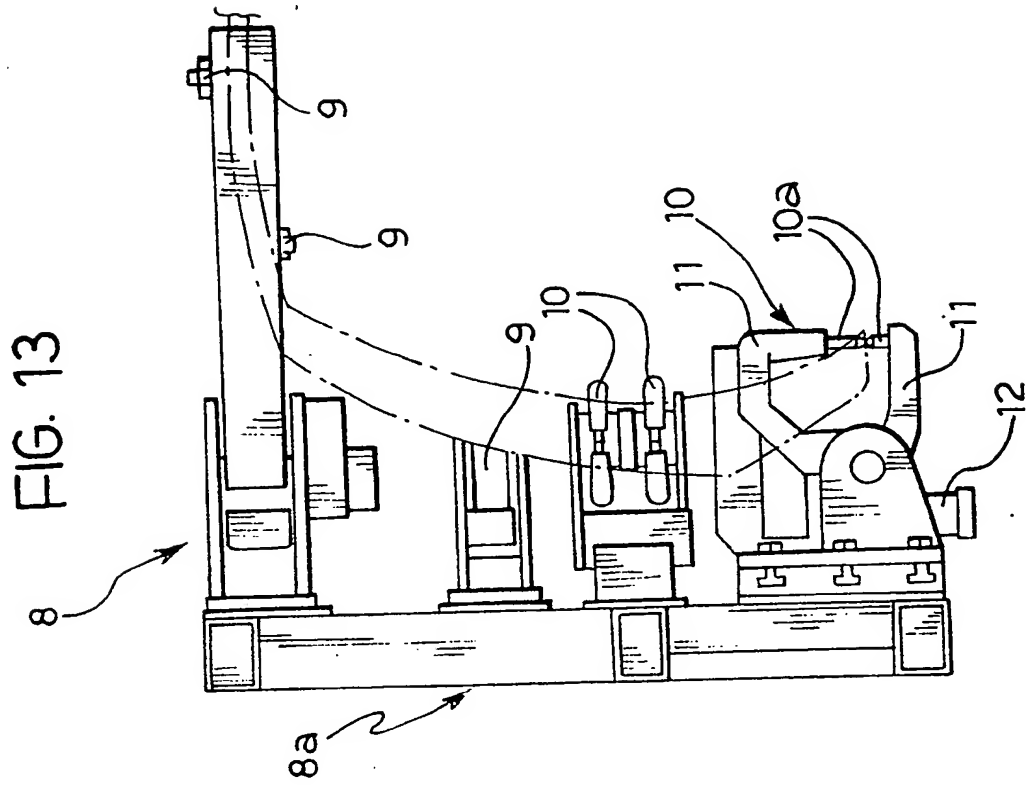
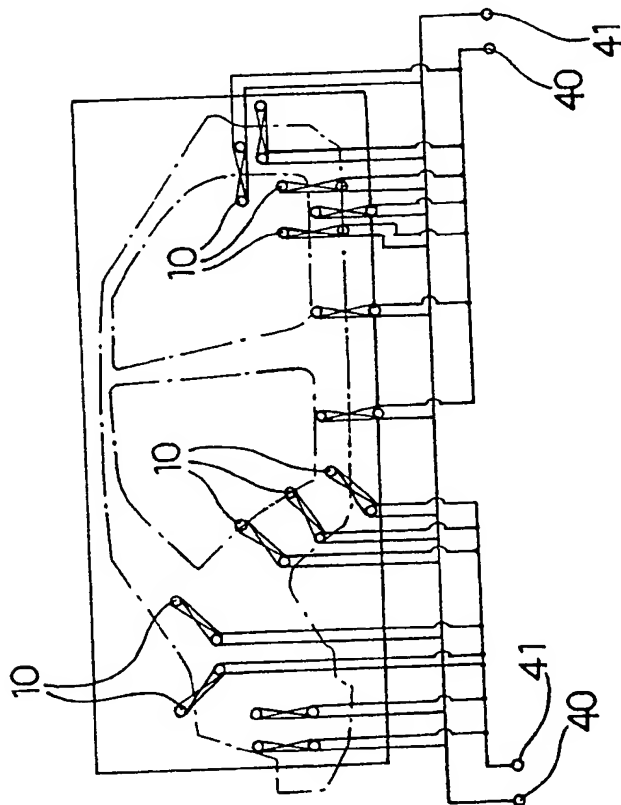
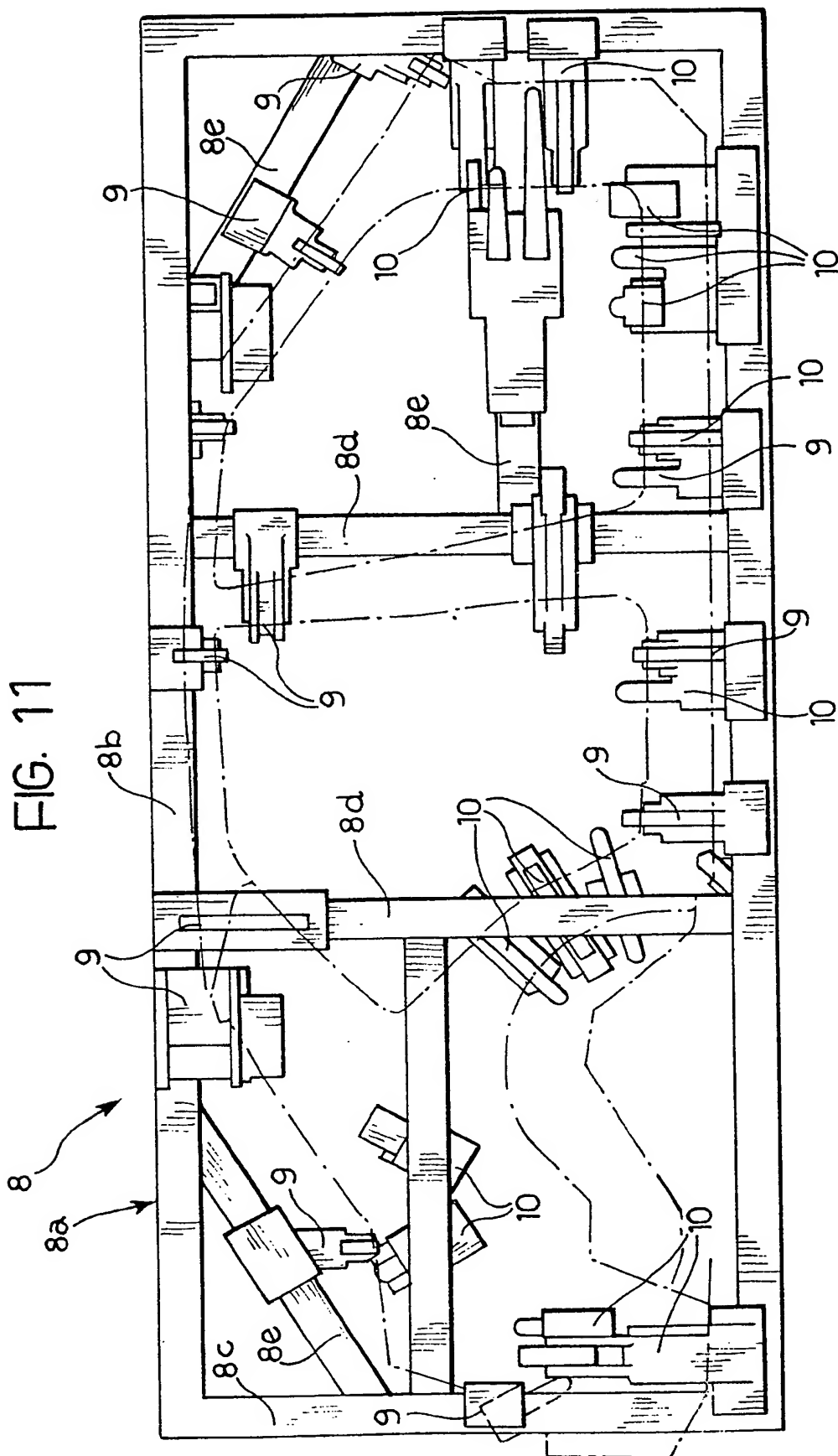
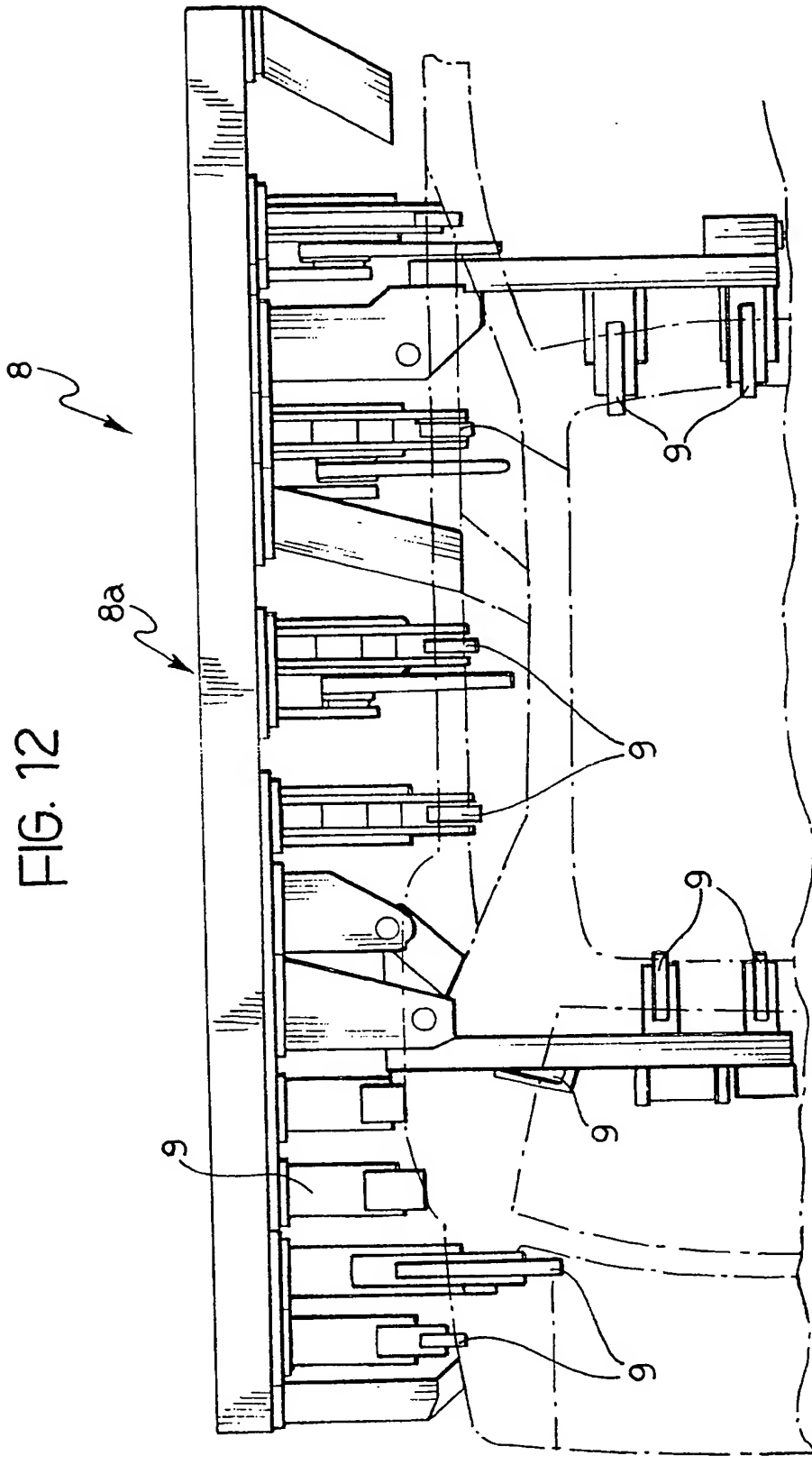


FIG. 10







(19)



Europäisches Patentamt
European Patent Office
Office européen des brevets



(11) Publication number:

0 351 377 A3

(12)

EUROPEAN PATENT APPLICATION

(21) Application number: 89830295.5

(51) Int. Cl.⁵: **B23K 37/04**

(22) Date of filing: 27.06.89

(30) Priority: 13.07.88 IT 6766188

(43) Date of publication of application:
17.01.90 Bulletin 90/03(84) Designated Contracting States:
AT BE CH DE ES FR GB GR LI LU NL SE(88) Date of deferred publication of the search report:
09.01.91 Bulletin 91/02(71) Applicant: **COMAU S.p.A.**
Via Rivalta 30**I-10095 Grugliasco (Torino)(IT)**

(72) Inventor: **Alborante, Giancarlo**
Via Aldo Moro, 1
I-10028 Trofarello (Torino)(IT)
Inventor: **Graciotti, Rinaldo**
Corso Laghi, 81/105
I-10090 Buttigliera Alta (Torino)(IT)

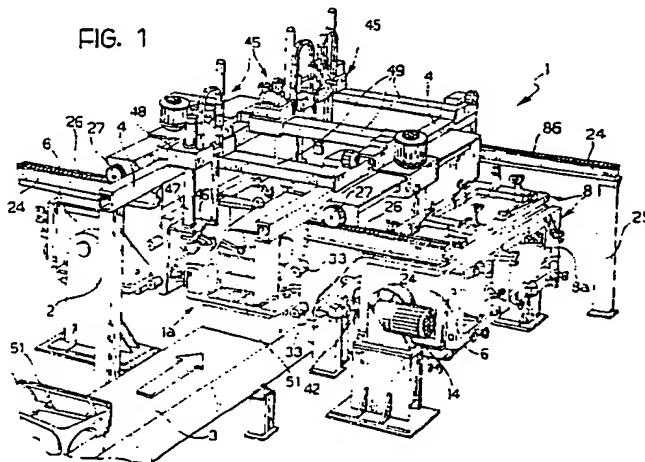
(74) Representative: **Notaro, Giancarlo et al**
c/o Jacobacci-Casetta & Perani S.p.A. Via
Alfieri, 17 17
I-10121 Torino(IT)

(54) **Apparatus for welding motor vehicle bodies.**

(57) Apparatus for welding loosely pre-assembled motor vehicle bodies (51) comprises a station (1) for locating and welding the body, a conveyor line (3) for transporting the loosely preassembled bodies (51) to the station (1), at least two pairs of locating gates (8) situated at the two sides of the station (1), each pair of locating side gates (8) being provided with locating devices (9) engageable with the body (51) and adapted to the specific geometric shape of a particular type of body, gate conveyor means for

bringing a pair of side gates (8) corresponding to the type of body which is in the welding station (1) into correspondence with an operative position in the welding station (1), and at least one welding device (10) for welding the body. At least one drum (6) rotatable about an axis parallel to the longitudinal direction of the body in the welding station and carrying on its periphery a plurality of locating gates (8) suitable for various types of body is provided on each side of the conveyor line.

FIG. 1

**EP 0 351 377 A3**



European
Patent Office

EUROPEAN SEARCH REPORT

Application Number

EP 89 83 0295

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.5)
X	DE-A-3 414 387 (KUKA SCHWEISSANLAGEN + ROBOTER GMBH) " the whole document "	1,2	B 23 K 37:04
A	GB-A-2 157 237 (FATA EUROPEAN GROUP SPA) " the whole document "	1-3	
A	GB-A-2 126 174 (G. DI ROSA) " the whole document "	1-3,7	
A	DE-A-2 819 616 (BAYERISCHEN MOTOREN WERKE AG) " the whole document "	1,4	
A,D	FR-A-2 383 818 (WELDESIGN) " the whole document "	1,3	
A,D	US-A-4 162 387 (E. DE CANIDA)		
The present search report has been drawn up for all claims			TECHNICAL FIELDS SEARCHED (Int. Cl.5)
			B 23 K
Place of search		Date of completion of search	Examiner
The Hague		16 November 90	ARAN D.D.
CATEGORY OF CITED DOCUMENTS X: particularly relevant if taken alone Y: particularly relevant if combined with another document of the same category A: technological background O: non-written disclosure P: intermediate document T: theory or principle underlying the invention E: earlier patent document, but published on, or after the filing date D: document cited in the application L: document cited for other reasons &: member of the same patent family, corresponding document			